

## PROBLEM 27

### 3 Convolutional Network Architecture\*\*

Consider the following 1D input and two convolutional filters:



- Convolve the first filter with the input.
- Convolve the second filter with the input.
- What would the output of the convolutional layer look like with both filters?
- In the previous part, the spatial size of the output decreased from that of the original input -ie. it had fewer neurons. In some settings, we preserve the size by applying zero padding. What would the output of the convolutional layer look like in this case?
- Continuing to use zero padding of size 1, we now use a stride length of 2. What is the output of the convolutional layer now? Compare how this relates to the case with no stride.
- If our filters were size 5, rather than size 3, with stride 1, how much padding would you apply to maintain output size?
- What is a general expression for the output size (number of neurons) in a convolutional layer, in terms of the filter size ( $F$ ), stride length ( $S$ ), amount of padding ( $P$ ), and the input size ( $W$ )?
- Consider a  $10 \times 10$  grayscale image input (no RGB channel). If you made a 1-layer fully connected network, with 1 hidden, how many weight parameters would be required in the hidden layer including bias terms (ignore the output layer)?
- Consider a  $10 \times 10$  grayscale image input (no RGB channel). If you made a 2-layer fully connected network, with 10 and 5 hidden units respectively, how many weight parameters would be required in these hidden layers including bias terms (ignore the output layer)?
- With the same  $10 \times 10$  input image, you now use a convolutional layer with  $F = 2$  (square filters),  $S = 2$  (in both dimensions), and  $P = 0$ . How is the output volume of the first convolutional layer with 2 filters, including bias terms?
- One advantage of convolutional networks is that the number of free parameters can be controlled by parameter sharing for a filter across spatial dimensions. Each filter is replicated across the entire visual field (image). That is, if a filter is used at one spatial coordinate  $(x_1, y_1)$ , the same weights are also used in a different position  $(x_2, y_2)$ . Adopting the parameter sharing scheme, how many parameters does the convolutional layer have?